

Lecture 10: Wrapping up connectedness

Last time: Connectedness
Today: path-connectedness

{ Revision of connectedness.

Def. A top sp (X, \mathcal{T}) is disconnected if

$\exists U, V \in \mathcal{T}$ such that

$$U \neq \emptyset, \quad U \cap V = \emptyset, \quad U \cup V = X.$$

It's called connected if not disconnected.

Think-pair-share: Connected or disconnected?

$X = \mathbb{R} \setminus \{0\}$, \mathcal{T} = subspace topology in \mathbb{R}

Disconnected: $U = \mathbb{R}_{<0}, \quad V = \mathbb{R}_{>0}$.



$X = \mathbb{R}$, $\mathcal{T} = \mathcal{T}_{\text{Standard}}$

Connected: $X = \bigcup_{n=1}^{\infty} [-n, n]$ (see last week!)

$X = \mathbb{R}$, $\mathcal{T} = \mathcal{T}_{\text{cofinite}} = \{U \subseteq X : U = \emptyset \text{ or } \#(x \in U) < \infty\}$

Also connected: $\mathcal{T}_{\text{cofinite}} \subseteq \mathcal{T}_{\text{Standard}}$

Making the topology coarser just makes it harder to find a disconnection!

$X = \mathbb{R}$, $\mathcal{T} = \mathcal{T}_{\text{trivial}} = \{\emptyset, X\}$

Connected: Same reason!

$X = \mathbb{R}$, $\mathcal{T} = \mathcal{T}_{\text{discrete}} = \mathcal{P}(X)$

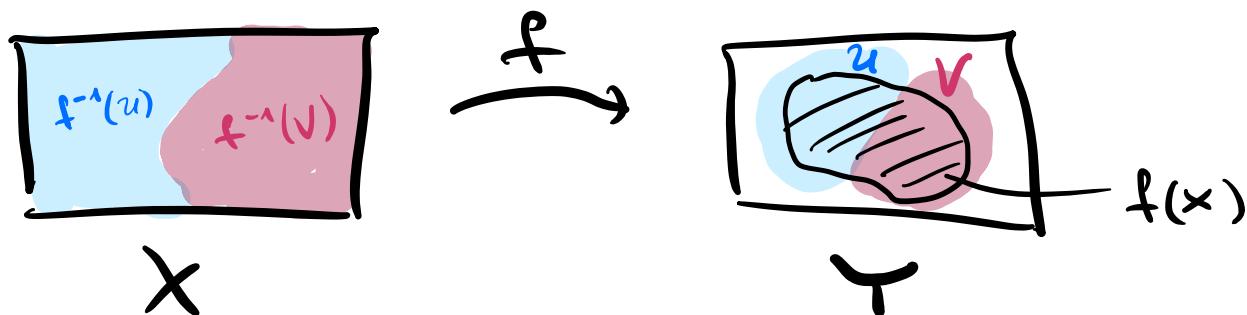
Disconnected: $U = \mathbb{R}_{<0}$, $V = \mathbb{R}_{\geq 0}$.

Prop. Let $f: X \rightarrow Y$ be a continuous map. Then

$[X \text{ connected}] \Rightarrow [f(X) \text{ connected}].$

↑ with subspace topology in Y

Picture:



Prop (Lemma 8.15). Let (X, τ_x) be a top sp., and $A \subseteq X$. Then

$$[A \text{ connected}] \Rightarrow [\bar{A} \text{ connected}].$$

with subspace topology in X

Pf. Contraposition! Suppose \bar{A} is disconnected.
Then there exists $U, V \in \tau_{\bar{A}}$ such that

$$\begin{array}{lcl} U \cap \bar{A} \neq \emptyset & (U \cap \bar{A}) \cap (V \cap \bar{A}) = \emptyset & \bar{A} = (U \cap \bar{A}) \cup (V \cap \bar{A}) \\ V \cap \bar{A} \neq \emptyset & \downarrow \text{intersect both sides with } A & \downarrow \text{intersect both sides with } A \\ \left. \begin{array}{l} U \cap A \neq \emptyset \\ V \cap A \neq \emptyset \end{array} \right\} \text{property of closure} & (U \cap A) \cap (V \cap A) = \emptyset & A = (U \cap A) \cup (V \cap A) \end{array}$$

Conclude: A is disconnected!

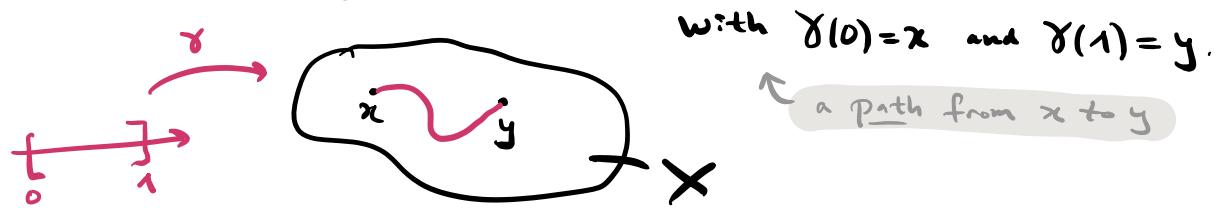
□

Ex: $X = \mathbb{R}$ $\tau_x = \tau_{\text{standard}}$, $A = (0, 1)$ $\bar{A} = [0, 1]$ both connected
(see last week!)

Path connectedness

Def. A topological space (X, τ) is path connected if

$\forall x, y \in X \quad \exists$ continuous map $\gamma: [0, 1] \rightarrow X$



Prop. Let $f: X \rightarrow Y$ be a cont. map. Then

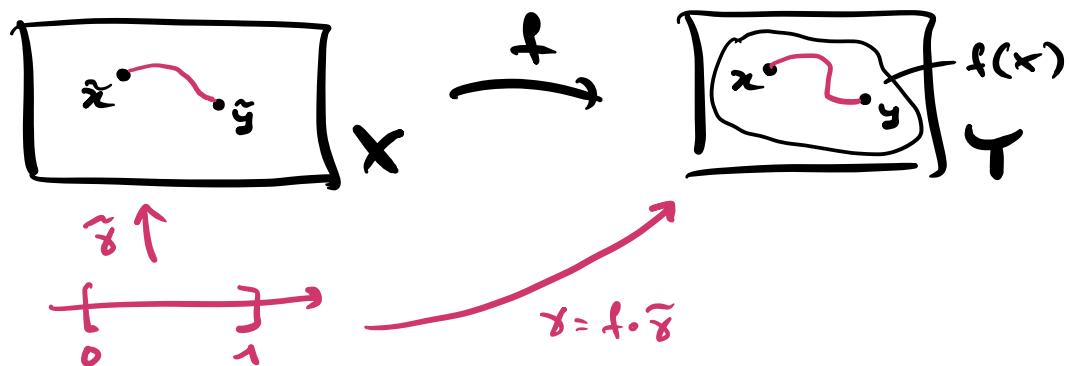
$$[X \text{ pathconnected}] \Rightarrow [f(X) \text{ pathconnected}].$$

Pf. Let $x, y \in f(X)$. Then there exists $\tilde{x}, \tilde{y} \in X$ s.t. $x = f(\tilde{x})$, $y = f(\tilde{y})$.

By pathconnectedness of X , there is a path $\tilde{\gamma}: [0, 1] \rightarrow X$ from \tilde{x} to \tilde{y} .

Then $\gamma = f \circ \tilde{\gamma}: [0, 1] \rightarrow f(X)$ is a path from x to y . \square

Picture:



Prop. Let (X, τ) be a top sp. Then

$$[X \text{ pathconnected}] \Rightarrow [X \text{ connected}].$$

Pf. Suppose for a contradiction that X is pathconnected but not connected, s.e. $\exists U, V \in \mathcal{T}$ such that

$$U \neq \emptyset, \quad U \cap V = \emptyset, \quad U \cup V = X.$$

By nonemptiness, we can find $x \in U, y \in V$.

By pathconnectedness, we can find cont. map

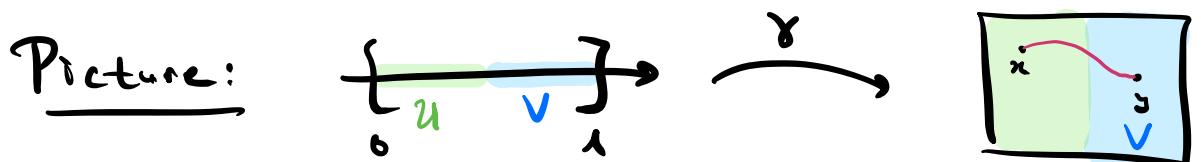
$$\gamma: [0,1] \rightarrow X \text{ with } \gamma(0) = x, \gamma(1) = y.$$

$$\text{Then } [0,1] = \gamma^{-1}(x) = \gamma^{-1}(U \cap V) = \gamma^{-1}(U) \cup \gamma^{-1}(V),$$

$$\gamma^{-1}(U) \cap \gamma^{-1}(V) = \gamma^{-1}(U \cap V) = \gamma^{-1}(\emptyset) = \emptyset,$$

$$\gamma^{-1}(U) \neq \emptyset \text{ b/c } \gamma(0) = x \in U, \quad \gamma^{-1}(V) \neq \emptyset \text{ b/c } \gamma(1) = y \in V,$$

which contradicts the connectedness of $[0,1]$. \square



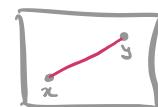
Think-pair-share: Pathconnected or not?

$$X = \mathbb{R}^n, \quad \mathcal{T} = \mathcal{T}_{\text{standard}}$$

Pathconnected:

$$\gamma: [0,1] \rightarrow X$$

$$\gamma(t) = (1-t)x + ty$$



$$X = \mathbb{D}^n, \quad \mathcal{T} = \mathcal{T}_{\text{cofinite}}$$

Also pathconnected: $\mathcal{T}_{\text{cofinite}} \subseteq \mathcal{T}_{\text{standard}}$

Easier for a map to be continuous w.r.t a coarser topology on the codomain!

$$X = \mathbb{R}^n, \quad \mathcal{T} = \mathcal{T}_{\text{discrete}}$$

Not pathconnected b/c not connected.

$$X = \mathbb{R} \setminus \{0\}, \quad \mathcal{T} = \text{subspace topology on } \mathbb{R}.$$

Not pathconnected. Same reason.

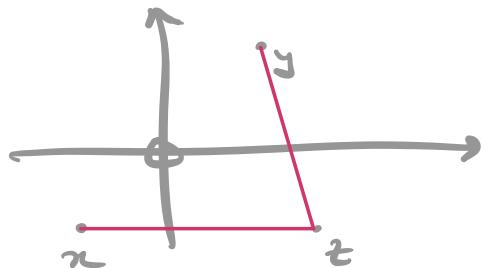
$$X = \mathbb{R}^n \setminus \{0\} \text{ for } n > 1, \quad \mathcal{T} = \text{subspace topology on } \mathbb{R}^n$$

Pathconnected: Let $x, y \in X$.

If 0 is on the line segment between x and y , take a detour:

$$\gamma: [0, 1] \rightarrow X$$

$$\gamma(t) = \begin{cases} (1-2t)x + 2t z & \text{for } t \in [0, \frac{1}{2}] \\ (2-2t)z + (2t-1)y & \text{for } t \in [\frac{1}{2}, 1]. \end{cases}$$



Remark. We can use pathconnectedness to show $\mathbb{R} \neq \mathbb{R}^n$ for $n > 1$.

⚠️ Not immediately obvious: look up "space-filling curves"!

If there were a homeomorphism $\varphi: \mathbb{R} \rightarrow \mathbb{R}^n$,

then the restriction $\tilde{\varphi} = \varphi|_{\mathbb{R} \setminus \{0\}}: \mathbb{R} \setminus \{0\} \rightarrow \mathbb{R}^n \setminus \{\varphi(0)\}$

would be a homeomorphism, but homeomorphisms preserve pathconnectedness! ↴

More generally: $\mathbb{R}^m \neq \mathbb{R}^n$ for $m \neq n$ (see AlgTop 1).

The topologist's sine curve

Example of a connected but not pathconnected space!

117 in the (fantastic!) book "Counterexamples in topology"

$$A := \left\{ \left(x, \sin\left(\frac{1}{x}\right) \right) : x \in (0,1] \right\} \subseteq \mathbb{R}^2$$

Both pathconnected and connected
Since it's the image of the cont map
 $(0,1] \rightarrow \mathbb{R}^2$
 $x \mapsto (x, \sin(\frac{1}{x}))$

$$X := \overline{A} \subseteq \mathbb{R}^2$$

Note: X is connected b/c connectedness is preserved under closure.

Will turn out: Not pathconnected!

Observation: $X = A \cup (\{0\} \times [-1,1])$

Pf. \square Let $y \in [-1,1]$. Note that

$\left(\left(\frac{1}{\pi n + \arcsin(y) + 2\pi k}, y \right) \right)_{n=1}^\infty$ is a sequence in A converging to $(0,y)$ in \mathbb{R}^2 .
 $\rightarrow (0,y) \in X = \overline{A}$.

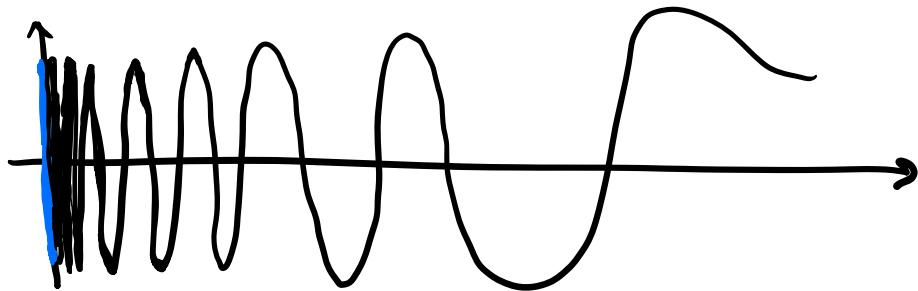
\square Let $(x,y) \in \mathbb{R}^2$ s.t. there exists a sequence

$$\left(\left(x_n, \sin\left(\frac{1}{x_n}\right) \right) \right)_{n=1}^\infty \rightarrow (x,y)$$

$x_n \in [0,1] \forall n \Rightarrow x \in [0,1]$ If $x > 0$, then continuity and $x_n \rightarrow x$ implies $\sin\left(\frac{1}{x_n}\right) \rightarrow \sin\left(\frac{1}{x}\right)$
 $\sin\left(\frac{1}{x_n}\right) \in [-1,1] \forall n \Rightarrow y \in [-1,1]$ but $\sin\left(\frac{1}{x_n}\right) \rightarrow y$ so uniqueness of limits in \mathbb{R} gives $y = \sin\left(\frac{1}{x}\right)$, i.e. $(x,y) \in A$.

(conclude: $(x,y) \in X$). \square

Picture:



Claim: X is not path connected

Pf. Assume for a contradiction that it is.

In particular, \exists path $\gamma: [0,1] \rightarrow X$ with $\gamma(0) = (0,0)$ and $\gamma(1) = (\frac{1}{\pi}, 0)$.

Notation: $\gamma_x = \tau_x \circ \gamma: [0,1] \rightarrow \mathbb{R}$ x-coordinate of γ $\left. \begin{array}{l} \text{continuous} \\ \text{maps.} \end{array} \right\}$

 $\gamma_y = \tau_y \circ \gamma: [0,1] \rightarrow \mathbb{R}$ y-coordinate of γ

Key idea: γ will have trouble leaving the vertical line segment continuously.
We will show this by keeping track of the hilltops and valleys of A .

Note: $\gamma_x(0) = 0$ and $\gamma_x(1) = \frac{1}{\pi}$, so by the intermediate value theorem

$$\exists t_1 \in (0,1) \text{ s.t. } \gamma_x(t_1) = \frac{1}{3\pi/2} \longrightarrow \gamma_y(t_1) = -1$$

Repeated application of the IVT gives

$$\exists t_2 \in (0, t_1) \text{ s.t. } \gamma_x(t_2) = \frac{1}{5\pi/2} \longrightarrow \gamma_y(t_2) = 1$$

$$\exists t_3 \in (0, t_2) \text{ s.t. } \gamma_x(t_3) = \frac{1}{7\pi/2} \longrightarrow \gamma_y(t_3) = -1$$

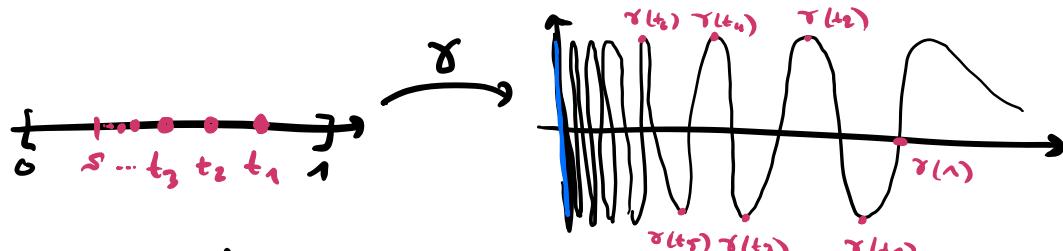
Keep going to get a sequence $t_1 > t_2 > t_3 > t_4 > \dots > \Delta$

such that $\gamma_x(t_n) = \frac{1}{(2n+1)\pi/2}$ and $\gamma_y(t_n) = (-1)^n$.

The sequence $(t_n)_{n=1}^{\infty}$ is decreasing and bounded from below.

Hence, $t_n \rightarrow s$ for some $s \in [0,1]$.

Picture:



Now, we're in trouble!

By continuity of γ_y , it should hold that

$$\gamma_y(t_n) \rightarrow \gamma_y(s)$$

But this is impossible, since

$\gamma_y(t_n) = (-1)^n$ alternates between ± 1 .



Conclusion: X is not pathconnected. □

Remark. For many well-behaved spaces such as

manifolds (spaces that locally look like \mathbb{R}^n for some $n \in \mathbb{Z}_{\geq 0}$)

connectedness actually implies pathconnectedness, b/c they are locally pathconnected. See §8.3 in the book (optional reading).

Exit ticket: True or false?

- If X is connected, and \sim is an equivalence relation, then X/\sim is also connected. True: $X/\sim = \pi(X)$ for the continuous quotient map $\pi: X \rightarrow X/\sim$ $x \mapsto [x]$

- X pathconnected $\Rightarrow X/\sim$ pathconnected True: Analogous.

- X disconnected $\Rightarrow X/\sim$ disconnected False: $X = \mathbb{R} \setminus \{0\}$, with trivial equivalence relation $x \sim y \quad \forall x, y \in X$ X disconnected, but $X/\sim \setminus \{\infty\}$ is connected.

Example:
 \mathbb{RP}^n (path-)connected
for all $n \in \mathbb{Z}_{\geq 0}$.

To look forward to in the exercises:

- All spaces can be partitioned into connected components.
- $SO(3) \subseteq \mathbb{R}^{3 \times 3}$ is pathconnected. ←
- $GL_3(\mathbb{R})$ and $O(3)$ have two connected components each!

Hint: Look up Euler's rotation theorem to get a feel for how you can move around inside $SO(3)$

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Euler's Rotation Theorem states that any orientation-preserving isometry (rigid motion) of a sphere is equivalent to a rotation by some amount about some axis. As the earth rotates randomly in the animation below, the red line indicates the axis around which the earth must be rotated from its current position to regain its starting position. Thus the isometry given by movement of the earth from its starting position to its current position is the opposite rotation (again about the red line). To see the rotation back to the starting position, click anywhere on the figure. Click again to resume the random wobbling.

